Generation of Rotationally Symmetric Micro Tools using

Ultrashort Laser Pulses

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1. Introduction

Lathe turning is, along with, e.g., cutting and drilling, an important and widespread procedure of machining parts of various materials. In this particular process, the work piece rotates around its axis while the lathe chisel is guided alongside the material, thus realizing the geometry of the rotationally symmetric part. However, this mechanical approach holds multiple disadvantages such as wearing of the tool or occurring shear forces, which tend to negatively affect the process. As a consequence, imprecise dimensional accuracy, chipping of brittle materials or even breakage of the part may occur.

Changing the mechanical lathe chisel to a focused ultrashort pulsed laser beam, however, circumvents these disadvantages. This non-contact tool of the highest precision impinges the constant rotating workpiece tangentially. This particular micro machining of geometry is referred to as laser turning, upon which the laser beam is, in general, oriented perpendicularly to the rotational axis and tangentially to the work piece. The target geometry is realized by moving the laser beam and adjusting the feed rate alongside the work piece while the R-axis implements the rotatory motion as depicted in Fig. 1.

The experiments were carried out on a four-axis laser machine (WS Multihead, Optec S.A. Belgium). The X, Y and Z axes are used for positioning the laser beam and adjusting the feed rate alongside the work piece while the R-axis implements the rotatory motion as depicted in Fig. 1.

The laser turning process has shown potential regarding part roundness $^7$ and displayed advantages in the generation of tools in terms of occurring processing forces as well as tool wear $^8$. The most common applications of laser turning are dressing, conditioning or profiling of grinding wheels. Thereby, the laser beam is used to restore the abrasive surface of the wheel, either by melting off a surface layer and exposing new grains or by precise material removal to achieve pre-specified flank geometries $^9$–$^{14}$. Furthermore, ultrashort pulsed laser turning can be used to manufacture dental ceramic implants, as shown by Ackerl et al. $^{15}$.

While cutting, drilling and structuring of materials with ultrashort laser pulses are prevalent processes $^{16}$, the tangential turning operation is still in need of far-reaching exploration and establishment. In this paper, we present a comprehensive study of a tangential laser turning process to generate rotationally symmetric parts from stellite rods using ultrashort laser pulses. Our results highlight that this femtosecond laser lathe process features a promising method for hard to machine materials on a micro scale.

2. Materials and methods

2.1 Laser system

The experiments were carried out on a four-axis laser micro machining station (WS Multihead, Optec S.A. Belgium). The X, Y and Z axes are used for positioning the laser beam and adjusting the feed rate alongside the work piece while the R-axis implements the rotatory motion as depicted in Fig. 1.

An ultrashort pulse laser system (Carbide, Light Conversion Lithuania) with a maximum average output power of
50 W and a wavelength of 1030 nm was deployed. At a repetition rate of 100 kHz, a maximum pulse energy of 500 µJ is achieved. The pulse length of the laser can be set between 0.24 ps – 10 ps. The laser beam is focused by a cutting head with a focal length of 50 mm, resulting in a calculated focal spot diameter of approximately 18 µm. A nozzle orifice diameter of 0.5 mm was chosen and the initial nozzle to work piece distance was set to 1.5 mm. A constant flow of Nitrogen at approximately 15 l/min was applied as processing gas to firstly guard the lens of the processing head from ablated material and secondly to ensure a continuous removal of debris from the work piece.

2.2 Materials and process characterization

Stellite rods (quality K-44 UF, 88 % WC, 12 % Co) with an initial diameter of 1.13 mm were chosen as test material. With a flexural strength of >4000 N/mm² it is applicable for drilling or shaping of high temperature resistant alloys, cast iron, stainless steels or titanium alloys. The rods are processed tangentially while rotating around their axis at a speed of 500 rpm as depicted in Fig. 2. The focused laser beam is guided parallel to the rotation axis of the work piece. The distance between the outer circumference and the laser tool path is referred to as offset. Depending on the initial work piece diameter, the offset defines, together with the applied pulse energy and the laser spot radius, the ablation depth in the material and thus concludes the final contour of the generated geometry. Therefore, the maximum ablation depth of this process is limited to the chosen offset plus the laser spot radius. Hence, this process is self-limiting in such a way that the chosen offset defines the nominal applicable ablation area. Throughout the process, the laser focal plane is kept on the same level as the rotation axes of the work piece.

The correlation of the rotation speed \( R \) of the work piece, the feed rate \( \dot{x} \) of the laser alongside the rotation axes and the laser spot diameter \( d_s \) affect the result of the laser turning process. Exceeding the critical feed rate \( \dot{x}_{\text{crit}} = R \cdot d_s \) causes a separation of the processing paths on the cylindrical surface of the work piece as shown in Fig. 3, potentially and inadvertently creating a thread.

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\[
\dot{x} \leq R \cdot d_s \quad \text{and} \quad \dot{x} > R \cdot d_s
\]

For determining the ablation rate, the initial and the final diameter are measured with an optical microscope. The ablation rate \( \dot{V} \) is calculated according to

\[
\dot{V} = \left( \left( r_0^2 - r_1^2 \right) \cdot \pi \right) \cdot \dot{x}
\]

with \( r_1 \) representing the inner (final) radius, \( r_0 \) the outer radius and \( \dot{x} \) the relative speed of the laser alongside to the rotation axis (cf. Fig. 2).

The arithmetic average roughness \( R_a \) was measured by a laser scanning microscope (Keyence VK – X200, Keyence Corp.).

3. Results and discussion

3.1 Influence of pulse length on ablation rate and efficiency

To characterize the effect of the laser pulse length onto the laser turning process, a series of studies are conducted to investigate its impact on the ablation rate at increasing pulse energies. The initial work piece diameter is 1.13 mm, the offset is set to 100 µm and the feed rate 0.05 mm/s. The ablation rates for pulse lengths of 0.24 ps, 1 ps and 10 ps are summarized in Fig. 4.

The presented results are single measurement values. However, the results are based upon several preliminary
tests, which substantiate their credibility as well as their replicability.

Apparently, for the laser turning process a shorter pulse length is beneficial in terms of achievable ablation rate, independent of pulse energy, which is in agreement with the results of Neuenschwander et al. [17].

Independent of the pulse length, the ablation rate increases with pulse energy. While the slope of the 1 ps and 10 ps curve seem to saturate at pulse energies of 400 µJ and 450 µJ, respectively, the pulse energy dependence of the ablation rate for a pulse length of 0.24 ps appears to reach its maximum for higher fluencies beyond 500 µJ. The highest removal rate of 1.27 mm³/min achieved in this study is reached at a pulse length of 0.24 ps and a pulse energy of 500 µJ.

Fig. 5 depicts the ablation efficiency, defined by the ratio of ablation rate and the applied laser power. A maximum ablation efficiency of 0.16 (mm³/min)/W can be reached with a pulse length of 0.24 ps and an applied pulse energy of 50 µJ. A shorter pulse length proves to be beneficial for increasing the ablation efficiency. Again, this behavior is in accordance to previous studies [17]. When the pulse energy is increased, a decrease in efficiency can be observed for each tested pulse length.

The relatively low ablation rate and ablation efficiency compared to conventional, perpendicular laser machining with ultrashort laser pulses is contributed to the high angular beam incidence during processing. The reflectivity of the surface can be described by the Fresnel-Equations [18] for orthogonal and parallel polarized waves as:

\[ r_x = \frac{n_1 \cos \theta_1 - n_2 \cos \theta_2}{n_1 \cos \theta_1 + n_2 \cos \theta_2} \]  
\[ r_y = \frac{n_2 \cos \theta_1 - n_1 \cos \theta_2}{n_2 \cos \theta_1 + n_1 \cos \theta_2} \]  

The resulting absorptivity is given by \( A = 1 - R \). Fig. 6 illustrates the angle dependent absorption for perpendicular and parallel polarization for metal based on equation (2) and (3) with the refractive indices \( n_1 = 1 \) (air) and \( n_2 = 3.08 \) (Tungsten, Ordal et al. [19]).

With the initial workpiece diameter of 1.13 mm and an offset of 100 µm, the incident beam angle calculates to approximately 55°. With an undefined orientation of the linear polarized incident laser beam, the absorbed laser power can decrease significantly. Parallel orientation of the polarization linked with an angularly optimized offset, on the other hand, can drastically improve the absorption and therefore increase the ablation rate and the overall efficiency of the laser turning process.

### 3.2 Influence of pulse length on surface topography

To survey the influence of the applied pulse length onto the forming surface, a series of roughness measurements after the laser turning process was performed. Pulse lengths of 0.24 ps, 1 ps and 10 ps and pulse energies between 50 µJ and 500 µJ were applied, whereas the arithmetic mean deviation of the roughness profile was measured. The measurements were taken after two consecutive passes of each parameter. The resulting values are depicted in Fig. 7.

The graph indicates that pulse lengths of 1 ps and less result in similar surface qualities with a roughness \( R_a \) of approximately 0.21 µm for all examined pulse energies. The lowest roughness of 0.17 µm is measured for a pulse length of 0.24 ps and a pulse energy of 250 µJ. At a pulse length of 10 ps, however, the roughness increases significantly for pulse energies of 350 µJ and above, suggesting an increase in melting effects. The microscope image of the study with a pulse length of 10 ps is shown in Fig. 8. Starting at 50 µJ (left), a gradual increase of the pulse energy by 50 µJ per step results in the mentioned melting of the surface at 350 µJ and above, which is in accordance with Fig. 7.
An inspection by a scanning electron microscope (SEM) reveals that all achieved surfaces show laser induced periodic surfaces (LIPSS) as shown in Fig. 9. These structures are formed through linear polarized fs-laser pulses and are oriented perpendicular to the incident laser polarization [20]. LIPSS occur at a laser fluence close to the material specific ablation threshold fluence and form on various materials [20–23]. Due to the periodicity close to the laser wavelength, the structures can be categorized as low spatial frequency LIPSS (LSFL) [24]. The formation of these structures is in the laser turning process unaffected by the applied pulse energy, as they appear even after high fluence processing (e.g. Fig. 9c).

We assume that because of the high angular beam incidence and the thereby caused high reflectivity of the material, the necessary low fluence regime for the generation of LIPSS is reached at the outer region of the processing laser spot. Hence, the occurrence of LIPSS is currently speculated to be the limitation of achievable roughness in the laser turning process.

3.3 Tool generation

The shaping of material in the laser turning process is, except from rotational symmetry and undercuts, freely selectable. Fig. 10 shows an SEM image of an exemplary geometry manufactured through this process.

A variety of shapes such as spheres, arcs and angles of different sizes are possible. Ninety-degree angles, however, are limited by the laser spot radius. Also, when ablating a large amount of material, debris may accumulate on perpendicular features. However, debris can in general be easily removed by sonicating the part. Laser turning can be, much like mechanical lathing, grouped in two processing steps: roughing and smoothing. During the roughing process, the approximate contour is realized while ablating the majority of material. Throughout the smoothing process, the exact outline of the part is realized while only removing little amounts of material. In contrast to mechanical lathing, however, both processing steps can be accomplished with the same tool by simply adjusting the feed rate and pulse energy. The overall processing time of the work piece shown in Fig. 10 is about 5 min, highlighting the speed and flexibility of the laser turning process.

4. Conclusion

In this report the process of tangential laser turning with ultrashort laser pulses was investigated. Subject of the studies was the influence of pulse length and pulse energy on the feasible ablation rate, efficiency and roughness. Furthermore, a possible influence of the incident laser polarization was discussed. An ablation rate of 1.27 mm³/min was achieved and an efficiency of up to 0.16 (mm³/min)/W was demonstrated. The smoothest surface was measured with an arithmetic mean deviation roughness of 0.17 µm. A shorter pulse length has proven to be beneficial for the laser turning process, both in terms of ablation rate and roughness. Long pulse durations above 1 ps along with high fluencies cause melting effects and negatively affect the processing results. Furthermore, the formation of LIPSS was illustrated and identified as a possible limitation of the achievable roughness. The findings in this report will contribute to foster the development of miniature rotationally symmetric parts and tools.

References


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