

High-Precision Surface Profiling Using Multi-Hundred Watts Ultrashort Pulse Lasers and Ultrafast Polygon-Mirror Based Scanner

Stefan Mauersberger¹, Joerg Schille¹, Kristian Kujawa¹, Lutz Schneider¹,
Christoph Million², Konrad Hartung², Karsten Oehlert² and Udo Loeschner¹

¹ University of Applied Sciences Mittweida, Laserinstitut Hochschule Mittweida,
Technikumplatz 17, 09648 Mittweida, Germany
E-mail: mauersbe@hs-mittweida.de

² Jade Hochschule Wilhelmshaven/Oldenburg/Elsfleth, Institut für Energie- und Verfahrenstechnik,
Friedrich-Paffrath-Straße 101, 26389 Wilhelmshaven, Germany

High-precision surface profiling is studied by using ultrashort pulse lasers up to 450 W laser powers and 40 MHz maximum pulse repetition frequency. A polygon-mirror based scan system is applied for ultrafast and flexible laser beam raster scanning providing up to 560 m/s laser beam moving speeds. By investigating the high-average power picosecond and femtosecond laser systems in large-area processing, optimum parameter settings are derived with regard to machining quality, efficiency and throughput. In addition, the influence of the focus spot size on top width and tip angle of trapezoidal micro structures (Riblets) is evaluated. Inspired by bionic surface functionalities, the laser made Riblets are tested in a Goettingen-type wind tunnel to identify their effectiveness for aerodynamic drag reduction in turbulent flows. For the optimum Riblet geometries, a maximum total pressure loss reduction of 1.76% is achieved that is remarkable when comparing with literature data. The drag reducing effect of the Riblets is further confirmed by empirical-analytical and CFD analyses showing up to 6.4% skin friction reduction. By taking into account the effective processing time of 6.0 cm²/min with potential to be further scaled-up with higher laser powers, ultrafast laser-based Riblet profiling could be a key enabling technology to enhance the operational performance in the energy machinery sector.

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1. Introduction

High-rate laser material processing by combining powerful ultrashort pulse lasers with high-speed laser beam scanning seems to be a key enabling technology for high-throughput and precision micro fabrication [1, 2]. In particular, ultrafast laser beam movement of hundreds meters per second and above is the core feature to bring high-average power lasers supplying multi-hundreds Watts from the laboratory state to industrial production. In fact, this is valuable for power scaling in high-volume laser machining as the processing rates scale-up with pulse repetition frequency and average laser powers. Hereby, the main advantage of the ultrafast laser beam moving speed is avoiding adverse effects on laser beam matter interactions even for MHz-repetitive laser pulses. So, it has already been reported for highly-repetitive ultrashort pulses that both machining quality and processing efficiency suffer from high thermal load to the substrates resulting in material melting as well as beam shielding losses affected by pulse – plasma/particle interactions. However, high-rate machining by speeding up the laser beam can overcome the main limitations of highly-repetitive ultrashort pulses when applied at comparably slow speeds, thus in order to sustain high processing quality and removal efficiency in high-throughput micro machining. This will be demonstrated in the following by the example of high-rate surface profiling using an ultrashort pulse laser with up to 450 W laser powers and 40 MHz maximum pulse repetition frequency. For ultrafast and flexible laser beam

raster scanning, an in-house developed polygon-mirror based biaxial scan system was applied providing up to 560 m/s laser beam moving speeds.

In the presented study investigating powerful picosecond and femtosecond laser beams, the peak fluence, pulse repetition frequency, average laser power and scan speed were varied in order to evaluate their influence on materials ablation. Based on the results obtained, the dependency of the studied processing parameters on the removal rate will be discussed and optimum parameter settings will be derived with regard to machining quality, efficiency and throughputs. Inspired by bionic surface functionalities, large-area Riblet production will be presented to demonstrate the potential of the high-rate laser profiling method for innovative surface engineering and productions. Laser made Riblet structures on surfaces in turbulent flows have already proven efficient to reduce skin friction drag and total pressure losses [3-5].

From this point of view, laser made Riblets provide a great potential to significantly increase performance and efficiency in the energy machinery sector, however, the high demand on the Riblet profile accurateness, low applied laser powers and the long processing times of only a few cm²/h hindered so far the industrial implementation of this innovative technology. These technological limitations can be overcome by high-rate machining using high-average laser powers in combination with ultrafast processing speeds that will be addressed in the following by the example of high-precision Riblet profiling.

2. Ideal Riblet geometry

Riblets represent rib-shaped micro-scale groove structures directed longitudinal along the flow of a fluid over a solid surface. They act to avoid interactions between the turbulent boundary layer and solid surface to be effective to reduce wall shear stress and skin friction drag. This is valuable for enhancing the operational performance of a large number of aerodynamic and hydrodynamic systems, e.g., windmill blades, turbine blades, aircraft wings, propellers, pipeline or ship applications, etc. The characteristic geometry parameters of trapezoidal Riblet structures are illustrated in Fig. 1 with Riblet spacing, s , Riblet height, h , top width, t , and tip angle, α , calculated from the taper angle, β , of the Riblet walls. However, in order to achieve maximum skin friction drag reductions, the ideal Riblet geometry to be processed depends on the local flow characteristics.

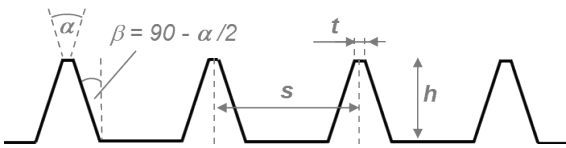


Fig. 1 Definition of the characteristic geometry parameters of trapezoidal Riblet structures.

In Fig. 2, as an example, the optimum Riblet spacing is calculated for the NREL S819 airfoil in the turbulent flow regime. The optimum Riblet spacing varies depending on the specific position along the airfoil length. As almost ideal value, a Riblet spacing of about $124 \mu\text{m}$ can be seen as effective over a great length along the given airfoil profile.

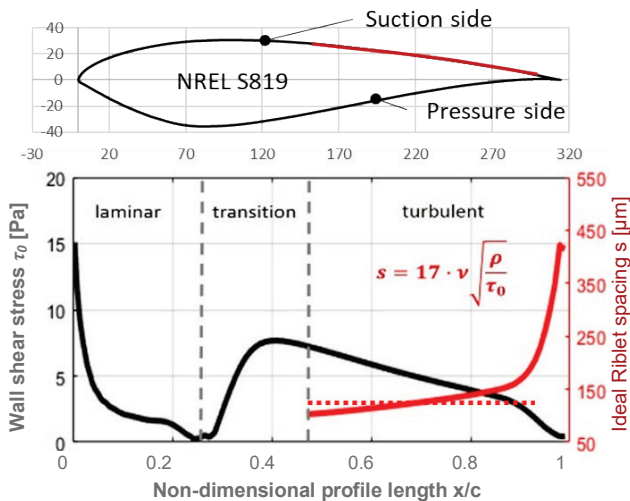


Fig. 2 Riblet spacing calculated for the NREL S819 airfoil as function of the specific position x along the airfoil length c ; the Reynolds number $\text{Re} = 10^6$ is considered in the calculations.

For most effective trapezoidal Riblets, the optimum Riblet height is given by half of Riblet spacing, the top width should be as small as possible and the tip angle should be 30° [6]. From this structural preconditions, several pre-investigations on flat plates were realized in order to optimise the laser profiling process parameters. Therefore, the following Riblet profile geometry is considered to be the optimum for the application on flat plates:

Riblet spacing:	$s = 124 \mu\text{m}$
Riblet height:	$h = 62 \mu\text{m}$
Top width:	$t < 10 \mu\text{m}$
Tip angle:	$\alpha = 30^\circ$

3. Analytical model to predict Riblet profiles

An analytical model is developed and applied to predict the resulting Riblet profile with the goal to adjust the parameter settings to be used in precision laser profiling. For a laser beam with Gaussian intensity distribution following Equation (1), and by taking into account Beer's law, the ablation profile resulting from single pulse irradiation can be calculated by Equation (2). Herewith, H_0 is the peak fluence as calculated from the pulse energy Q_p in Equation (3), $w_{\sigma,0}$ is the beam waist radius based on second order moments, d_z is the crater depth, H_{th} is the threshold fluence, and δ is the effective penetration depth.

$$H(r) = H_0 \cdot \exp\left(-\frac{2 \cdot r^2}{w_{\sigma,0}^2}\right) \quad (1)$$

$$d_z(r) = -\delta \left[\ln\left(\frac{H_{th}}{H_0}\right) + \frac{2r^2}{w_{\sigma,0}^2} \right] \quad (2)$$

$$H_0 = \frac{2 Q_p}{\pi w_{\sigma,0}^2} \quad (3)$$

Fig. 3 shows the ablated crater profile as function of fluence as the crater depth increases with higher applied fluence. Further, it becomes clear that the taper of the crater walls increases with greater crater depths. From this knowledge it can be concluded a greater depth is more likely the effect for steeper walls than the fluence. However, it should be mentioned here, thus to avoid misinterpretation of Fig. 3, the diameter of the modelled ablation craters scales in micrometer, as the depth is illustrated at nanometer scale.

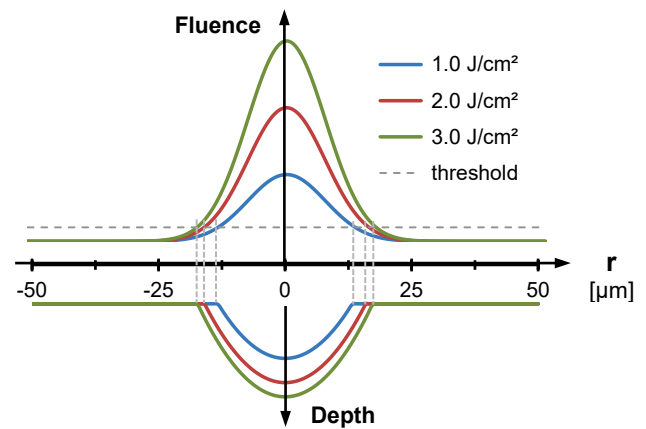


Fig. 3 Crater profiles calculated for pulses of various fluence.

The volume of a crater ablated by a single pulse can theoretically be determined by integrating the crater depth profile, as described and experimentally validated elsewhere [7-9]. For moving beams, however, the exact shape of the removed volume will be given by expanding this simulation to overlapping pulses [10]. Based on this approach, Fig. 4 plots fluence (top) and resulting depth profile (bottom) for eleven irradiated pulses moving along the x -axis at equidistant lateral pulse spacing dx .

$$z(x) = \delta \cdot \sum_{i=1}^n \left[\ln\left(\frac{H_{th}}{H_0}\right) + \frac{2 \cdot (x - i \cdot dx)^2}{w_{\sigma,0}^2} \right] \quad (4)$$

The resulting depth profile is calculated according to Equation (4) for pulses of 1.2 J/cm^2 peak fluence, $15 \mu\text{m}$ focus radius, $5 \mu\text{m}$ pulse spacing and by taking into account

0.1 J/cm² threshold fluence and 18 nm effective penetration depth. For clarity, only the pulse numbers 1 to 4 as well as 10 and 11 are illustrated in this figure.

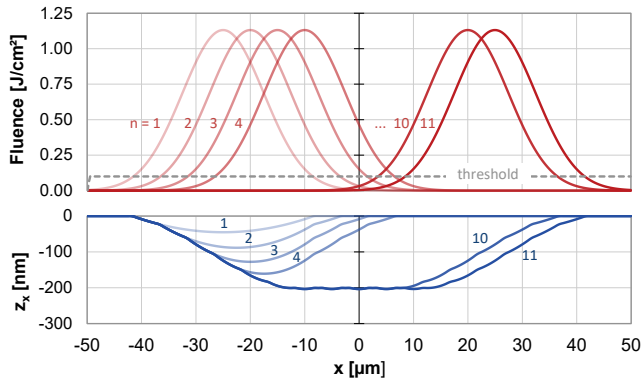


Fig. 4 Fluence (top) and resulting depth profile (bottom) for 11 irradiated pulses moving along X-axis at equidistant lateral pulse spacing dx ; colors changing from light to dark indicate higher the total optical energy input.

The simulation model was enhanced to sum up the depth profile of each individual scanned line in order to estimate the depth profile of the cavities engraved in parallel line-scanning procedure, see Fig. 5 illustrates the resulting depth profile computed for different focus spot diameters ranging between 10 μm and 46 μm . As the number of impinging pulses varied depending on the considered spatial pulse distance, herewith spatial pulse and line distances half of the respective spot radii were used, the number of scan crossings was varied in a way to produce 50 μm profile depth here.

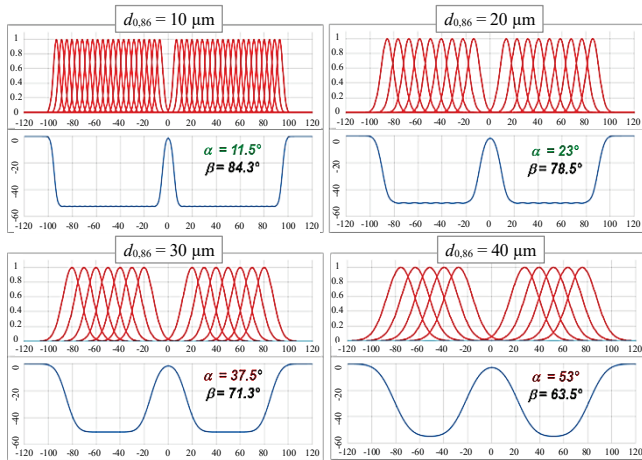


Fig. 5 Depth profile computed for different focus spot diameters $d_{0,86}$ ranging between 10 μm and 46 μm ; the taper angle β and respective tip angle α are indicated, the fluence was 1.2 J/cm², the number of scan passes was varied to achieve the requested 50 μm Riblet height.

It can further be seen in Fig. 5, the steepest taper angle will be achieved with the smallest focus spot, in fact decreasing from 84.3° to 63.5° for the spot diameters enlarging from 10 μm to 46 μm , respectively. The resulting tip angle α of the arising Riblet profile can be easily approximated from the taper angle β by the following simple equation

$$\alpha = 2(90^\circ - \beta) \quad (5),$$

where the taper angle calculates as function of profile depth D and focus spot radius w according to

$$\beta = \arctan\left(\frac{D}{w}\right) \quad (6).$$

From the calculated Riblet profiles it becomes clear, the candidate tip angle for functional Riblet can only be reached with 10 μm and 20 μm focus spot diameter. However, the profile calculations carried out in this work give evidence that even for large spot diameters wall angles steeper than 75°, or rather tip angles smaller than 30°, can be achieved at larger profile depths. This is indicated in Fig. 6 plotting the taper angle as function of profile depth. For different focus spot diameters ranging between 10 μm and 46 μm , the respective profile depths for either taper angle larger than 75° or tip angles smaller than 30° are highlighted in this figure. It is shown that a taper angle greater than 75° can be achieved with 10 μm spot diameter at 19 μm profile depth, for the 46 μm spot diameter the corresponding profile depth measures greater than 86 μm .

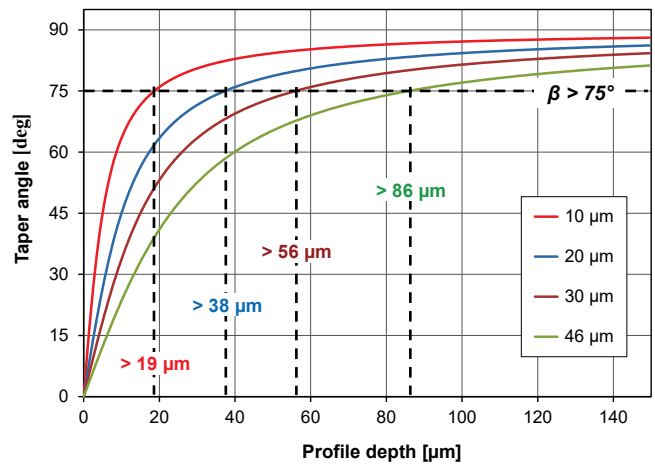


Fig. 6 Taper angle calculated as function of profile depth for focus spot diameters ranging between 10 μm and 46 μm , the respective profile depths for either taper angle larger than 75° or tip angles smaller than 30° are highlighted.

4. Experimental methods

In the experimental study, a variety of ultrashort pulse laser systems were applied. This provided a wide range of complementary processing parameter settings to be investigated on AISI 304 (X5CrNi18-10) stainless steel and EN-AW 5005A (AlMg1) Aluminum alloy metal sheets. In all experiments, the sample surface was positioned in the focal plane. The smallest experimentally studied focus spot diameter was 20 μm that was supplied by focusing a femto-second laser beam of 515 nm wavelength and 400 fs pulse duration and using a 160 mm f-theta lens. For the larger focus spots, a laser beam of 1030 nm and 400 fs was focused by either a 167 mm or 255 mm objective to achieve focus spot diameters of 30 μm and 46 μm , respectively.

At first, in the fundamental experimental work on laser profiling and Riblet formation, comparably low average laser powers up to 5.5 W were irradiated to the samples at 1.03 MHz pulse repetition frequencies. Herewith, a galvanometer scan system was used to deflect the laser beam at 5 m/s scan speed thus to provide the required 5 μm spatial pulse distance. Secondly, to demonstrate scaling-up the profiling machining process with increasing average powers, both a picosecond laser delivering 10 ps pulses at 230 W and a femtosecond system supplying 350 fs pulses at 450 W

maximum average laser powers were studied. For efficient processing even at such high average powers, and further to avoid laser beam shielding losses and thermal loading, highly repetitive pulses up to 40 MHz were deflected at extremely high 560 m/s beam moving speeds. For this high-speed beam scanning, a polygon-mirror based scan system was implemented instead of the galvanometer scanner, the latter providing only 18 m/s maximum scan speeds.

The machined Riblet structures were analyzed by using the confocal microscope VK-X260K (Keyence) for topography and profile depths measurements. The high precision of machining was visualized by scanning electron microscope (SEM) micrographs captured with the JSM-6510LV (JEOL). The functionality of the laser made Riblet was evaluated by wind channel measurements in turbulent flows. From these measurements, the overall drag reduction was deduced by the ratio of the respective pressure loss coefficient $\Delta\omega/\omega_0$ determined for both the smooth and the Riblet metal plates. In order to validate the drag reducing effect, the Riblet profiles were further analyzed by an empirical-analytical and a numerical approach to predict the achievable wall shear stress reduction with reference to the smooth surface $\Delta\tau/\tau_0$. In addition, to relate the predicted wall shear stress reduction to the wind tunnel measurements, the reduction of the pressure loss coefficients $\Delta\omega/\omega_0$ and wall shear stress reduction $\Delta\tau/\tau_0$ were computed by Computational Fluid Dynamic (CFD) methods [11]. It is noteworthy, therefore, stream-wise wall shear stresses cause skin friction drag, for example reported for an Airbus A340-300, that contribution to the total drag of the aircraft was about 48% [3].

5. Experimental results and discussions

5.1 Characteristics of laser profiling

Fig. 7 shows SEM micrographs of Riblets as representative examples for the micro structures made by high-precision laser surface profiling. The Riblets were machined in AISI 304 by multiple raster-scanning a 1030 nm femtosecond laser beam of 30 μm focus spot diameter, 4.3 W applied average laser powers, and 1.03 MHz pulse repetition frequency at 5 m/s scan speed. The shown Riblet structures vary in their spacing and height as produced by increasing the number of adjacent lines within the raster scan pattern as well as the number of repeated scan passes. In this manner, the Riblet height corresponds to the depth of the laser machined cavities double-sided the remaining walls (Riblet). Due to the fact that none rectangular side-walls could be produced, the resulting height profile corresponded to a trapezoidal Riblet shape.

Following a general trend in laser micro processing, the cavity depth, or rather Riblet height, increased almost linearly with increasing number of scan passes. This is exemplified in Fig. 8 a by three-dimensional (3D) topography measurements on Riblets produced with 105 μm spacing. These Riblets were machined by using a laser beam of 20 μm focus spot diameter and 1.0 J/cm² fluence. The cavity depth increased from 8.8 μm achieved with 30 scan passes to 112.0 μm at 360 scans. The aforementioned linearly increase of the cavity depth with increasing number of scan passes is confirmed by the experimental data given in the plot of Fig. 8 b. The Riblet top width was typically measured below 10 μm for the cavities with depths greater than 50 μm . It can

also be seen that the experimental cross section profiles extracted from the topography measurements (symbols) are in good agreement with the computed ablation profiles (solid lines). Therefore, in the ablation profile computation following Equation (4), the fluence of 1.0 J/cm² and a varied number of scan passes applied in the ablation experiments were used, while the material-specific values were set to: threshold fluence of 0.07 J/cm² or 0.1 J/cm² and effective penetration depth of 12 nm or 18 nm for the 515 nm or 1030 nm laser beam, respectively, as well as a constant pulse and hatch distance of 5 μm was considered.

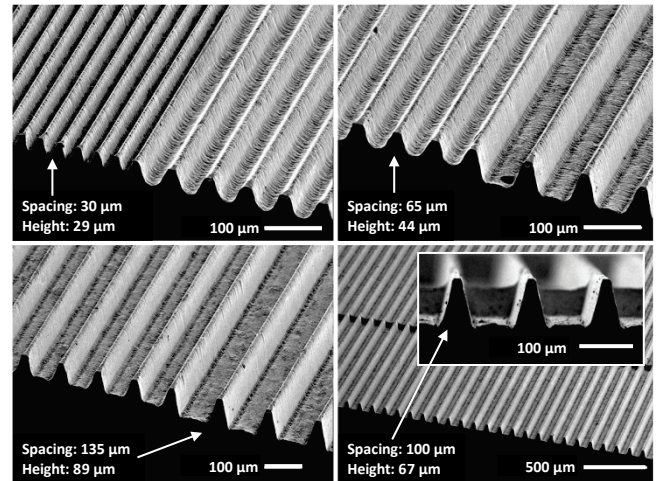


Fig. 7 Riblet structures made in AISI 304 by multiple raster-scanning a laser beam of 1030 nm, 390 fs, 1.03 MHz, 30 μm focus diameter and 4.3 W average laser power.

Exceptionally, the taper angles of the deeper laser processed cavities deviate from the computed profiles. It should be mentioned, therefore, that side-wall effects, i.e., dependence of reflectivity on angle of incidence, re-deposition of ablated material, etc., are not considered in the ablation model. In particular, re-deposition of ablated material at the cavity walls comes into greater effect at the deeper cavities. This effect is illustrated by the polished cross section micrograph included in Fig. 8 c (right). The taper angles were measured above 75° at cavities with depths greater than 40 μm . Such steep cavity walls fulfill the geometric precondition on functional Riblets regarding their tip angle.

As another effect, the influence of the focus spot diameter on both taper angle and top width is emphasized in Fig. 8. By comparing the data presented in Fig. 8 c and d, it comes clear that steeper cavities could be produced with the smaller 20 μm focus spot diameter compared to the larger ones of 30 μm . In detail, with a beam of 20 μm focus spot size the taper angle was measured of 78° at 43 μm cavity depths. This angle was considerably greater than that obtained with the 30 μm focus spot size of 70° at 44 μm depth. The respective tip angles correspond to 24° versus 40°. It is worth mentioning that the smallest top width of the Riblets of 6 μm was produced with the 20 μm focus spot size. With the 30 μm spot size the top width was larger than 10 μm . These findings are in good accordance with the computed Riblet profiles presented above. In conclusion, it is noteworthy that the profile requirements on functional Riblets could only be achieved with the 20 μm focused laser beam.

Fig. 9 presents the tip angle as a function of Riblet height by the example of two materials, AISI 304 and Aluminum

alloy EN-AW 5005A, as machined with different processing parameter settings. In Fig. 9 a, the tip angle of 30° is highlighted by a red solid line indicating the objective goal for functional Riblet structures.

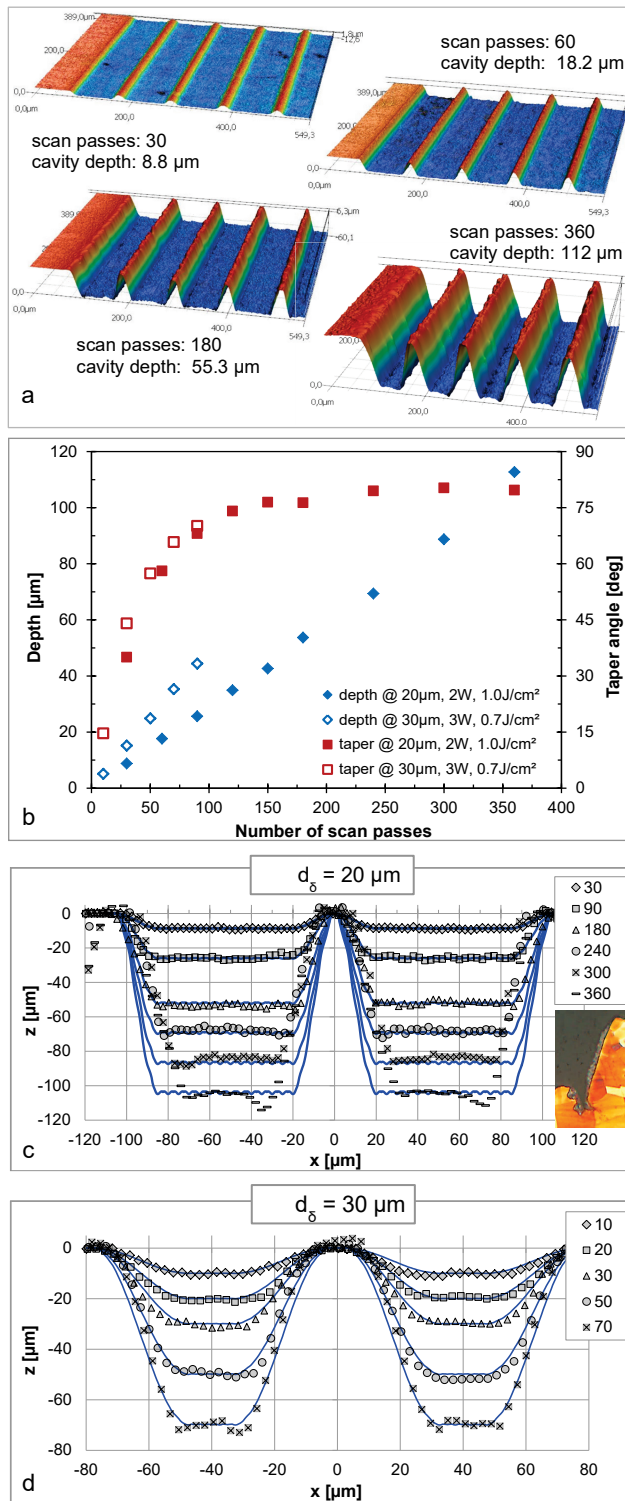


Fig. 8 a) 3D topography measurements on Riblets produced on AISI 304 with $105 \mu\text{m}$ spacing, processing parameter settings were: 515 nm , $20 \mu\text{m}$ focus spot, 1.0 J/cm^2 fluence, scan passes between 30 and 360; b) functional relation between cavity depth, taper angle and number of scan passes; Riblet formation as function of number of scan passes, experimental (symbols) and computed (solid lines) ablation profiles are shown, the focus spot diameter was varied between $20 \mu\text{m}$ (c) and $30 \mu\text{m}$ (d).

The figure shows the experimental results (symbols) in good correlation with the computed tip angles (dotted lines) within a wide range of investigated parameter settings. This, in turn, validates the proposed method to predict the resulting tip angle for diverse processing conditions. In detail, it is shown that tip angles smaller than 35° cannot be produced with $46 \mu\text{m}$ spot size. This was the case even for $120 \mu\text{m}$ high Riblets as presented in the figure by the example of EN-AW 5005A. However, tip angles much smaller than 30° can be produced with the smaller focus spot sizes. This is figured out by the example of AISI 304 at $30 \mu\text{m}$ and $20 \mu\text{m}$ focus spot size for Riblet depths greater than $70 \mu\text{m}$ or $40 \mu\text{m}$, respectively. Steeper Riblets walls with much smaller tip angles can be produced by further scaling down the focus diameter to $10 \mu\text{m}$, as pointed out in Fig. 9 a by the computed data. As another effect, the polarization direction of the laser beam is influencing the resulting tip angle that is presented for the $20 \mu\text{m}$ focus spot diameter. On AISI 304, the perpendicularly polarized laser beam (red symbols) led to less steep tip angles if compared with parallel polarized laser radiation (green symbols). An explanation therefore might be the lower absorptivity of laser radiation at perpendicular polarization state that will be confirmed in future experiments.

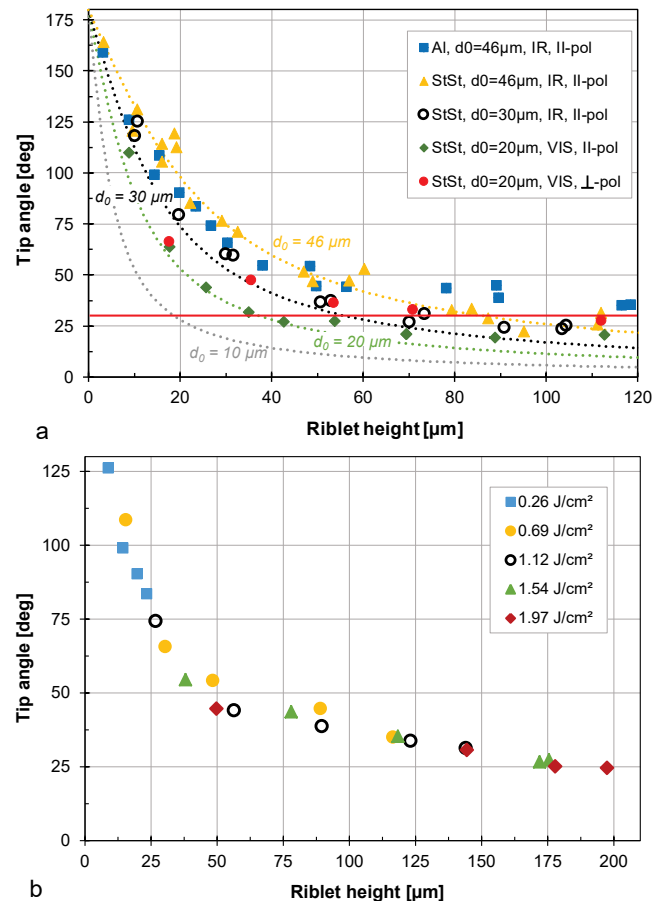


Fig. 9 Tip angle as function of Riblet height; a) focus spot diameter and polarization direction were varied on EN-AW 5005A and AISI 304; b) fluence was varied on EN-AW 5005A.

Another interesting finding in this study was the fluence of the irradiated ultrashort pulses has no significant influence on the tip angle. This can be seen in Fig. 9 b by the example of EN-AW 5005A. In the investigated fluence range starting

slightly above the threshold fluence from 0.26 J/cm² to 1.97 J/cm² almost identical tip angles were achieved at a distinct Riblet height unaffected by the fluence. This verifies that both focus spot diameter and Riblet height, or rather cavity depth, have the greatest effects on the tip angle.

Fig. 10 illustrates 3D topography measurements and a cross section optical micrograph of Riblets having profile geometry very close to the predefined ideal Riblet geometry. The characteristic profile data of the Riblets were measured of 105 μm spacing, 53 μm height, 24° tip angle and 5.8 μm top width. The Riblets were machined with a 515 nm laser beam, 20 μm focus spot diameter, 1.03 MHz pulse repetition frequency, and 1.7 W average laser power.

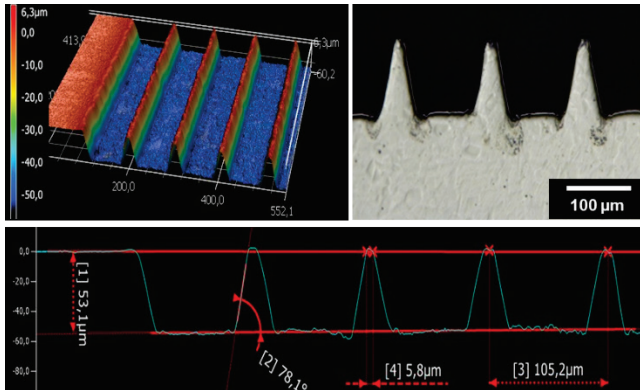


Fig. 10 Ideal Riblet geometry measured of 105 μm spacing, 53 μm height, 24° tip angle and 5.8 μm top width; processing parameter settings were: 515 nm, 20 μm focus spot, 1.03 MHz pulse repetition frequency, and 1.7 W average laser power.

5.2 Scaling-up the processing rates

The processing rate for the laser-made ideal Riblet structure shown in Fig. 10 was below 0.1 cm²/min that is clearly too slow for industrial production and manufacturing. However, high-rate laser machining seems a feasible technique to bring high-precision laser profiling from basic research to industrial-scale production. High-rate laser machining combines multi-hundreds Watt laser powers with ultrafast beam moving speeds capable to scale-up processing rates and machining throughputs increasing laser powers. In this way, the machining qualities can be maintained at sufficiently high level for precision micro processing, notwithstanding the fact that hundreds of Watts, extremely high, laser powers will be applied for high-speed machining. This is displayed in Fig. 11, comparing 62 μm deep Riblets of constant 124 μm spacing machined in AISI 304 with 1030 nm femtosecond pulses. The Riblets shown in Fig. 11 a were made by applying 3 W average laser powers at 1 MHz and 5 m/s scan speed. The resulting volume ablation rate was as low as 1 mm³/min. A considerably (almost linearly up-scaled) higher removal rate above 16 mm³/min was achieved with 60 W laser power, irradiated to the samples at 9.6 MHz pulse repetition frequency.

However, as indicated in Fig. 11 b-d, the spatial pulse overlap affected the processing quality. With the low processing speed of 48 m/s at the highest 9.6 MHz pulse repetition frequency, the pulse spacing was as small as 5 μm. This low spatial pulse spacing along with very short inter-pulse delays and high applied laser powers induced a high thermal load to the substrates. In consequence of this, the material melted and re-solidified that, in turn, lowered the Riblet

quality as exemplarily shown in Fig. 11 b.

Another detrimental effect of the low spatial pulse distance at such high pulse repetition frequencies can be deduced from Fig. 11 e. The removal efficiency reduced from 0.28 mm³/min/W at 20 μm pulse spacing to 0.22 mm³/min/W at 5 μm pulse spacing. This is potentially due to the shielding of the incoming laser beam by interaction of the next impinging laser pulses with the still existent plasma/particle plume induced by subsequent pulse irradiation(s). With the higher scan speed of 192 m/s both processing quality and removal efficiency could be improved, as shown in Fig. 11 c. The latter might result from heat accumulation thus enhancing material removal reported previously [12, 13]. By further increasing pulse spacing and scan speed, the processing quality was still excellent but both the specific removal rate and removal efficiency reduced.

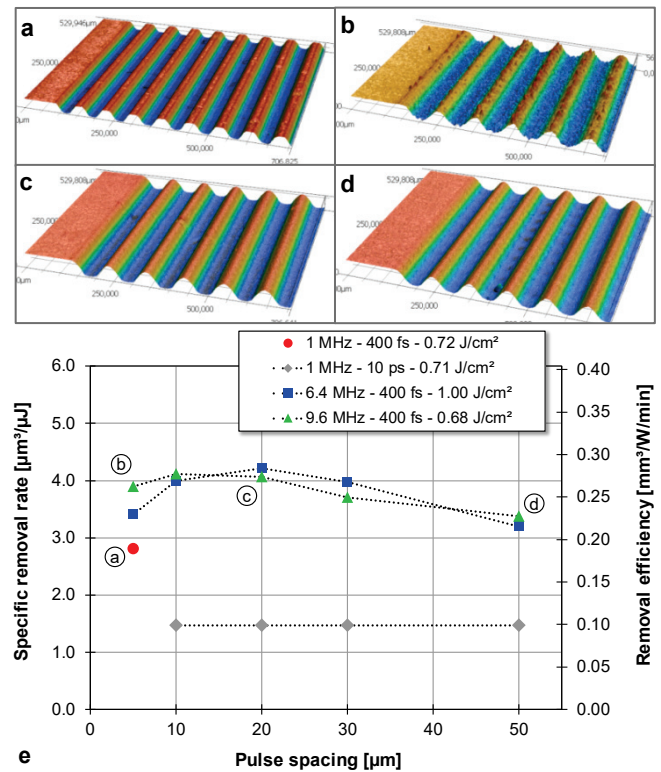


Fig. 11 Riblets machined in AISI 304 with 1030 nm femtosecond laser pulses and a) 3 W, 1 MHz, 5 m/s; b) 60 W, 9.6 MHz, 48 m/s; c) 60 W, 9.6 MHz, 192 m/s; d) 60 W, 9.6 MHz, 480 m/s; e) specific removal rate and removal efficiency vs. lateral pulse spacing, the Riblets a-d are referenced in e, dotted lines guide the eye.

This is pointed out in Fig. 11 d and e by the targeted 62 μm Riblets produced at 480 m/s scan speed and 9.6 MHz pulse repetition frequency. An explanation therefore can be seen in the applied high beam moving speed as the irradiated pulses moved ahead from the induced isotherms that, in turn, lowered the contribution/effectiveness of heat accumulation on material removal. In addition, almost identical removal rates were achieved for both 6.4 MHz and 9.6 MHz repetitive pulses. From this, it can be suggested that heat accumulation and particle shielding effects will be balanced at such high MHz pulse repetition frequencies. As another effect, the plot in Fig. 11 e confirms about 2.5 times higher removal efficiency for femtosecond pulses than for picosecond pulses, which is conformal to results achieved in earlier studies [14].

Power scaling of the area processing rate for the considered Riblets fabricated in EN-AW 5005A is presented in Fig. 12. It can be seen, the effective processing rate for the laser made 62 μm Riblet structures of 124 μm period increases from 1.5 cm^2/min at 90 W to 6.0 cm^2/min as achieved with 450 W average (fs) laser power. The area processing rate obtained with the 230 W picosecond laser beam was considerably lower of about 1.8 cm^2/min although the irradiated average laser power is about the half of the high-average power femtosecond laser beam.

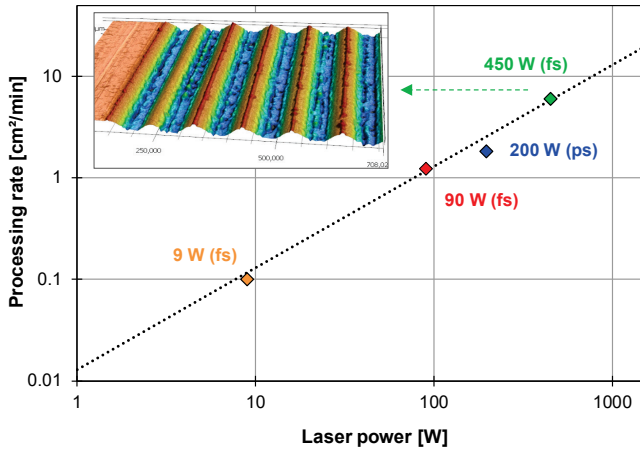


Fig. 12 Power scaling in large-area Riblet production on Aluminum alloy using femtosecond and picosecond laser beams; the dotted line indicates the scaling-up of the effective processing rates with higher laser powers for the targeted 62 μm height and 124 μm period Riblet geometry.

This fact emphasizes the already above mentioned greater efficiency for femtosecond instead of using picosecond laser pulses in material ablations. The 3D topography micrographs in the plot indicate material melting that lowers the Riblet quality. It is noteworthy for these very initial results, the fluence of the irradiated pulses was greater than optimum level that was applied here to bring the total of 450 W available laser powers to the substrate. For this case, the pulse repetition frequency was already set to maximum of 40 MHz and beam moving speed was ultrafast 560 m/s. A further improvement of the processing strategy can be seen in the combination of parallel processing using DOE (diffractive optical element) in combination with ultrafast (polygon scanner based) laser beam movements. This novel machining strategy has already been successfully demonstrated in large-area surface texturing [15] and will be investigated in high-precision surface profiling in future studies.

5.3 Functional testing of laser made Riblets

The functional testing of the laser made Riblets double-sided processed on flat metal plates (AlMg4,5Mn) was conducted in a Goettingen-type wind tunnel under turbulent air flow conditions. Fig. 13 depicts the real profiles of the tested laser made Riblets (red lines). In addition, the ideal trapezoidal Riblet geometry is indicated by black lines with the following characteristic profile values: Plate 1 and Plate 2 with 124 μm Riblet spacing and 62 μm Riblet height, Plate 3 with 178 μm Riblet spacing and 79 μm Riblet height. It can be seen, the profile of the laser made Riblets on Plate 1 deviates significantly from the ideal trapezoidal Riblet geometry.

This resulted primarily from the limited spatial resolution of the 46 μm larger spot size of the focused 1030 nm laser beam.

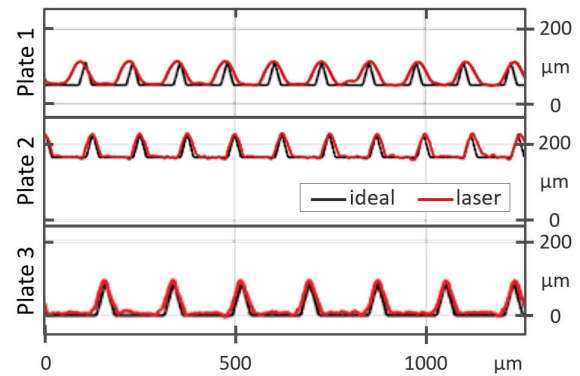


Fig. 13 Profile data of the laser made Riblets produced on the flat metal plates for wind tunnel testing. The ideal trapezoidal Riblet geometry is indicated by the black lines.

However, with 84.2 W average laser power and 140 m/s scan speed applied here for Riblet processing the highest effective processing rate of 1.5 cm^2/min was achieved. By contrast, Fig. 13 displays the profile of the Riblets produced on Plate 2 and Plate 3 in good conformity to the ideal Riblet profile. In this case, the 515 nm laser beam was focused to a smaller 25 μm spot size for the Riblet processing. The applied average laser power to produce the high-quality Riblets was only 8.2 W irradiated at 12.7 m/s scan speed. Therewith, the effective processing rates were achieved of 0.47 cm^2/min and 0.33 cm^2/min for the Riblet profiling on Plate 2 and Plate 3, respectively.

The drag reducing effect of the laser processed metal plates can be seen in Table 1. Therein, the total pressure loss reduction determined in the wind tunnel measurements as well as drag reduction obtained in both the empirical-analytical and Computational Fluid Dynamic analysis are presented. For comparison, the drag reduction computed for the ideal Riblet geometry is given in this table. The difference in the predicted total pressure loss reduction $\Delta\omega/\omega_0$ for the identical ideal Riblet profile on Plate 1 and 2 was due to the different size of the considered laser processed surface area. The deviation of the total pressure loss reduction for the ideal Riblets on Plate 3 in comparison to Plate 2 resulted from the different Riblet size and from additional variation of the flow conditions.

Table 1 Summary of drag reductions achieved in the wind tunnel measurements as well as determined in the empirical-analytical and Computational Fluid Dynamic analyses.

		Plate 1	Plate 2	Plate 3
$\Delta\omega/\omega_0$	wind tunnel	-0.79%	-1.76%	-0.22%
	CFD	-0.87%	-1.73%	-2.21%
$\Delta\tau/\tau_0$	empirical	-4.24%	-5.45%	-6.01%
	CFD	-4.45%	-5.35%	-6.43%
ideal Riblet	$\Delta\tau/\tau_0$	-7.90%	-7.90%	-7.90%
	$\Delta\omega/\omega_0$	-1.42%	-2.49%	-2.82%

For all the tested laser made Riblet profiles a remarkable drag reducing effect could be verified that is within the range of expectations for ideal Riblet geometries. In the wind tunnel measurements, the highest drag reduction of -1.76% was

achieved with the Riblet profile Plate 2. Herewith, the experimentally determined drag reduction is in good agreement with the computed data. Only for Plate 3, the modelled pressure loss coefficient $\Delta\omega/\omega_0$ could not be confirmed by the wind tunnel measurements. However, for this Riblet profile produced on Plate 3 it is noteworthy that both the empirical-analytical approach and also the CFD method showed the highest drag reducing effectiveness. This discrepancy will be clarified in the ongoing study.

As already stated above, it should be emphasized here again that the functionality of the Riblets highly depends on the ratio between top width and Riblet spacing. In this context, the drag reducing effect of the laser made Riblets tested in this study is compared to literature references. This is pointed out in Fig. 14 showing the drag reducing effect determined in the empirical-analytical approach and the CFD analysis for the laser made Riblet profiles tested here is in line with the reduction of the wall shear stresses experienced in earlier engineering studies [16].

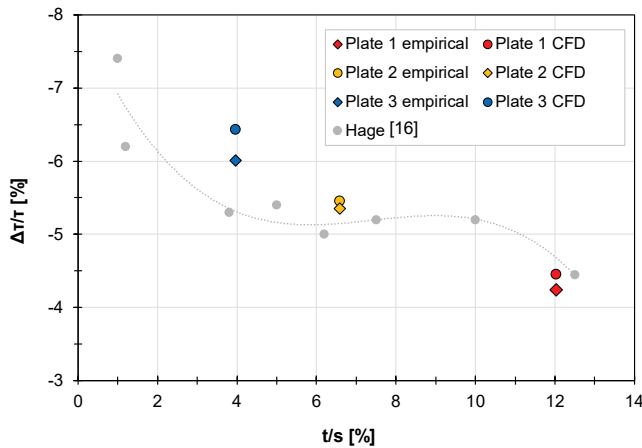


Fig. 14 Wall shear stress reduction $\Delta\tau/\tau$ as function of the ratio between Riblet top width and Riblet spacing; the wall shear stress reduction for Plate 1, Plate 2 and Plate 3 was obtained by considering the respective Riblet profile in the empirical-analytical and the CFD analyses; reference data from the literature are included [16].

Moreover, the laser made high-quality Riblet profiles presented in this work showed a more than twice higher skin friction drag reduction when comparing with previously laser-profiled Riblets tested in an oil channel [3]. As another positive effect of the high-rate laser processing technology applied here, the processing rates could be considerably increased by at least a factor of 20 for the 90 W or rather almost 100 for the 450 W femtosecond laser beam when compared to state-of-the-art laser processing.

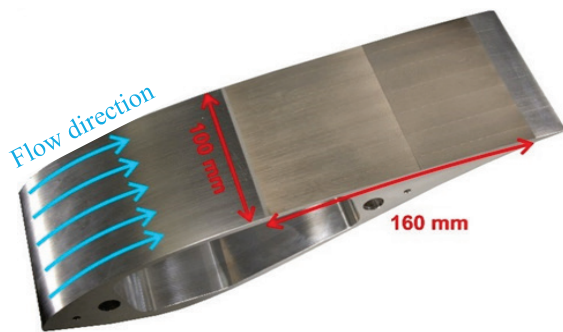


Fig. 15 Riblets produced on a NREL S819 airfoil (AlMg4,5Mn), the laser processed surface area is 160 mm x 100 mm.

These high processing rates attract the high-precision laser surface profiling method to be applied in modern micro fabrication. Therefore, as a first machining example given in Fig. 15, the Riblets were produced on a NREL-S819 airfoil thus to demonstrate the high potential of the laser profiling technology for innovative industrial applications in the energy machinery sector.

6. Conclusion

High-precision surface profiling was investigated in order to fabricate high-quality trapezoidal Riblet structures with potential for drag reduction in turbulent flows. At first, in the fundamental study, optimum laser machining conditions were defined to fabricate Riblets of pre-specified geometry for best functionality. The laser made Riblets were tested in a Goettingen-type wind channel but also in empirical-analytical and CFD analyses in order to evaluate their effectiveness for skin friction and total pressure loss reductions. A remarkable total pressure loss reduction as high as 1.76% was achieved in the wind tunnel measurements for the flat plates covered with optimal laser processed Riblet structures. The CFD analysis showed a maximum skin friction reduction of 6.43% for the laser made Riblet profiles. Applying the high-rate laser technology by combining high-average power ultrashort pulse lasers and polygon-mirror based ultrafast scan systems for Riblet profiling, an effective processing time of 6.0 cm²/min was reached. This is almost a factor 100 faster when comparing with state-of-the-art laser technologies. Furthermore, it was demonstrated in this study that the processing rates can be scaled-up with higher laser powers. So, in future, much greater processing rates can be expected for the higher available average laser powers applied in (parallel) ultrafast laser beam scanning. As a first machining example, the Riblets were produced on a NREL-S819 airfoil thus to demonstrate the high potential of the laser profiling technology for innovative industrial applications in the energy machinery sector.

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